

# 2023

# SCRAPY Coder User Manual Project number: 2021-1-FR01-KA220-SCH-000031617





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### 1. Introduction

The <u>SCRAPY Coder</u> is a drag & drop programming application, designed specifically for hosting a series of DIY projects based on the SCRAPY Kit. The programming environment is developed using <u>Google Blockly</u>, with several custom-made blocks of code to serve the requirements of the Kit's electronics, sensors, and components.

Using the Coder, an interested user can program several DIY electronic devices, learning at the same time physical computing concepts, and electricity and circuits paradigms. The Coder also provides the possibility to the user to create their own projects and program them using the coding environment.

This user manual will help users and educators get started with the SCRAPY Coder, understand its various functionalities and features, and finally become familiar with the Blockly programming environment in order to implement the Coder's projects as well their own.

# 2. Loging in

Accessing the SCRAPY Coder, can be done by visiting the project's website (<u>www.scrapykit.eu</u>) and simply click on the "Coder" button on the homepage.



Alternatively, users can use the following url: <u>www.coder.scrapykit.eu</u>.





First time users are required to create an account. At the login page, simply click on the "Register" button.

Login	
Email address	
Enter address	
Password	
Postsword	
Forgat your password? Register	
	unded by Decelorized epited

Fill in your information and click on "Register".





A pop-up message will appear after a successful registration. Click on "OK" and go to the login page by clicking on "Looking to login?". Additionally, a confirmation email will arrive at your inbox, verifying your registration.



At the login page, insert your email address and password, and click on "Let's go".







In case you forgot your password, simply click on "Forgot your password?", and you will be redirected on the password reset page. There, insert your email address and click on "Reset". An email containing further instructions will arrive at your inbox.

Re	set your password	
Email	laddress	
En	iter address	
	Reset	
	Looking to login?	
Contraction of the		

# 3. Home page

After successfully logging in to your account, you will be redirected to the Coder's homepage. There, the list of available projects will be presented, along with language selection options, progress status and some other information. Most of the Coder's features can be accessed through the navigation panel on the left side of the homepage.







#### 3.1. Language selection

On the top right corner, there is a language selector. Simply click on it and choose your preferred language. The SCRAPY Coder is provided in six languages: English, Greek, French, Portuguese, Croatian, and Dutch.



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#### 3.2. Progress

Directly under the language selector, there is a progress wheel. Each time you complete a project, the percentage will increase until you reach 100% completion.



#### 3.3. All Projects

The Coder provides access to 12 DIY projects, utilizing the SCRAPY Kit's electronics, sensors and other components. All projects have free access by simply clicking on the "Open" button.







By clicking on the "OPEN" button, the user will be directed to the coding environment for this specific project.



There, the user can see the Blockly coding environment, a description of the project, and a step-by-step guide for implementing the project.

Description
Through this activity, the user will experiment with building a reversing radar system using the Raspberry Pi Pico board and an HC-SR04 ultrasonic sensor. The user will acquire knowledge on:
1.The physics of ultrasonic waves and how they can be used to measure distance.
2.The basics of programming in Python and how to write code to control the Raspberry Pi Pico board.
3.1 he principles of circuit design and how to wire components together on a rapid prototyping board to create a functional reversing radar system.
By completing this project, the user will gain a deeper understanding of electronics, engineering, and
programming. They will also have a practical and useful device that they can use to make parking their car safer and more convenient.
fritzing





#### Step by Step

Connect the HC-SR04 ultrasonic sensor to the Raspberry Pi Pico board using connection wires.

Raspberry Pi Pico Board: GP15: Trigger pin of the HC-SR04 sensor GP14: Echo pin of the HC-SR04 sensor GP10: Positive pin of the green LED GP11: Positive pin of the orange LED GP12: Positive pin of the red LED GP2: Positive pin of the buzzer GND: Ground pin of the board

HC-SR04 Sensor: VCC: Connect to 5V power source.

GND: Connect to GND of Raspberry Pi Pico board Trig: Connect to GP15 of Raspberry Pi Pico board Echo: Connect to GP14 of Raspberry Pi Pico board

Next



In addition, there a few options on the top right corner related to the connectivity of the Raspberry Pi Pico.



To make the Coder interact with the physical world, you need to connect your Raspberry Pi Pico. The first step is to ensure your Pico has its firmware installed. Browse pages 12-19 of the SCRAPY Kit Manual if you are not sure how to do that. Make sure to close the Thonny Python application. Then, go to the project of your choice, and click on the Device option icon.



A list of all available devices, connected to your computer will pop-up. Choose the one called Board CDC. Then click "Connect".

<b>coder.scrapykit.eu</b> /blocklyProject?project_id=44e8f3aa-772b-4697-a		
coder.scrapykit.eu wants to connect to a serial port		
Board CDC (COM14)		
GEARMANAGER (COM3)		
Bluetooth Peripheral Device (COM4)		
Bluetooth Peripheral Device (COM5)		
VCOMM (COM6)		
Bluetooth Peripheral Device (COM7)		
BT SPP 2 (COM8)		
⑦ Connect Cancel		





You will get a message that the device is connected, which can also be seen in the top right corner.



Now, you are ready to start building your code for the project of your choice. Once ready, click on the Play button and see what happens in the physical world. You will also get a message that your program is running. If you need to stop your program, simply click on the Stop button.

#### 3.4. Navigation bar

The navigation bar on the left offers quick access to several features and information related to the Coder, as well as the project SCRAPY.







# 4. Blockly programming environment

Accessing the Blockly programming environment can be done by the navigation bar on the left by simply clicking on "BLOCKLY". The application will redirect you to the following interface:



Blockly gives a variety of blocks in order to build different programs depending on your needs. All blocks can be accessed through the "Blocks" bar on the left where all coding categories are displayed. Coding blocks can be dragged and dropped on the white coding space. Each category offers several coding options.

Logic	 Logic describes actions such as if statements and true/false conditions.
Loops	 Loops are control structures and repeat until a certain action occurs.
Mathematics	 Mathematics handles calculations and can also issue random numbers.
Text	 Text can access inputs and generate individual outputs.
Lists	 Lists create lists in combination with text or math elements.
Variables	 Variables can be used to assign pin numbers and other data.
Functions	 Functions describe the code behavior when a certain input is detected.
Digital Output	 Digital Output describes the state of a pin number (ON, OFF, TOGGLE).
Digital Input	 Digital input assigns pin number to sensors that require input from the environment.
PWM	 PWM provides custom coding blocks to electronics that require the PWM framework.
ADC	 ADC provides custom coding blocks to electronics that require the ADC framework.
DHT	 DHT is a custom block for using the DHT11 Temperature & Humidity sensor.
I2C	 I2C is a custom block for using the I2C framework, such as for the OLED display.
Ultrasonic	 Ultrasonic is a custom block for using the HC-SR04 ultrasonic sensor.
Interaction	 Interaction is a custom block for using the sleep library and for measuring time.





# 5. Badges

SCRAPY Coder awards completion badges for each completed project. These badges can be accessed through the navigation panel on the left, by simply clicking on "BADGES". In the Badges page, users can see the awarded badges which are marked as "complete".







# 6. **Projects solutions**

Project No 1 – DIY car backup sensor

set ultrasonic v to C HC-SR04 ultrasonic sensor with trigger 14 and echo 15			
set rad lad a to Output ain number 12			
set red_led v to Output pin number 12			
set yellow_led to Output pin number 11			
set green_led  to C Output pin number 10			
set buzzer to C Output pin number 2			
repeat while • C true •			
do set distance • to C Distance in cm Cultrasonic •			
if ↓ distance ▼ ≥ ▼ ↓ 20			
do Pin - State ON green_led •			
Pin - State OFF red led			
Pin - State OFF Vellow led			
Pin - State OFF huzzer			
else if distance - 5			
do Pin - State ON Vellow_led V			
Pin - State OFF red_led •			
Pin - State OFF green_led •			
Pin - State OFF buzzer			
else Pin - State ON red_led			
toggle buzzer •			
Pin - State OFF Vellow_led V			
Pin - State OFF red_led			
Sleep 0.1 seconds			





Project No 2 - Light-tracking servo motor

set servo 🔻 to 🕧 PWM for pin number 🕕				
set potentiometer_pin V to C ADC for GPI026 V				
set Idr_pin V to ADC for GPIO27 V				
repeat while V C true V				
do set potentiometer_value ▼ to ( Read ( potentiometer_pin ▼)				
set Idr_value V to ( Read [ Idr_pin V				
set angle ▼ to C Angle from potentiometer value C potentiometer_value ▼				
set speed V to C Speed from LDR value C Idr_value V				
Frequency 50 Servo V				
set duty V to L (angle V ÷ V 180				
set duty V to C round V ( duty V ÷ V ¢ 65025				
Duty_u16 servo v with cycle duty v				

Project No 3 – Spot the intruder







Project No 4 – Traffic light controller







Project No 5 – Move the motor with a joystick

o to map_value with: value, in_min, in_max, out_min, out_max
set value_in_min - to C value C in_min -
set out_max_out_min • to C Cout_max • • • C Cout_min •
set value_in_min_out_max_out_min  to C value_in_min  v  o out_max_out_min  v
set in_max_in_min • to C ( in_max • • • C in_min • )
set in_max_in_min_out_min * to ( ( in_max_in_min * ) + * ) out_min *
set map_value_return • to ( value_in_min_out_max_out_min • ) • • • • • • • • • • • • • • • • •
return 🖡 round 🔹 🖡 map_value_return 🔹
set x_axis_pin to 26 set servo_pin to 13 set servo_max_angle to 45 set servo_min_angle to 0 set x_axis_adc to ADC for pin GPIO26 * set servo_pwm to PWM for pin number 13 Frequency 30 servo_pwm * Duty_u16 with cycle 0 servo_pwm * repeat while * true * do set x_axis_val * to Read ( x_axis_adc * set angle_x * to map_value with: value x_axis_val * in_min 0 in_max_65535 out_min servo_min_angle * out_max_servo_max_angle *
Duty_u16   servo_pwm -
with cycle [ map_value with:
value ( angle_x -
in_min (_servo_min_angle *
out min ( 50
out_max ( 5000)
Sleep 0.5 seconds





Project No 6 - Object detection



#### Project No 7 - Gardening system







Project No 8 – Temperature station (Celsius, Fahrenheit)







Project No 9 - Fire alarm



Project No 10 – Smart clothes dryer







Project No 11 - Knocking light



Project No 12 – Sound detection warning alarm

